A nose is a nose is a nose?

Strickly speaking, there is no such thing as an electronic nose. But the term, which was introduced in scholarly literature in the early 1980s, has caught on and appears to be sticking, despite its being something of a technical community. After all, the photodetector that was automatically opening doors in the 1940s and earlier was termed electric eyes, but were a far cry from machine vision, let alone human vision.

The title of this special report is an even greater stretch—an elevating but more accurately termed electronic array for chemical sensing and identification. Scientists in several disciplines have been looking for missing elements in this complex puzzle for years, from both a physiological and an engineering standpoint. Yet a few systems, with admittedly limited goals, are exploiting recent advances in materials and signal processing to perform specialized tasks in reasonably robust ways.

Electronic noses for such applications as environmental monitoring, health care, and quality assurance of foods, have been available from vendors in several countries, and their use is expected to grow—read "The how and why of electronic noses," by H. Troy Nagle, Susan S. Schiffman, and Ricardo Gutierrez-Osuna (at right). The article also outlines the major transducer technologies (in one sense, the key component of an electronic nose), a few of which are then examined in "The electronic nose in Liliput," by Henry Bailes, Dirk Lange, and Andreas Koll, [pp. 35–38].

Can electronic olfaction ever hope to approach the sensitivity and scope of biology? Researchers would like to believe so, but the breakthrough may come only by abandoning the mimety of physiological transducers with hardware. The challenge is to model biological structures ranging from molecular chains to entile nerve paths. Articles on these design challenges in a bionose (as opposed to an electronic nose), and in biologically based ICs in general, will be addressed in an upcoming issue.

—Gadi Kaplan
Senior Technical Editor, &
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WITNESSING THE SWIFT ADVANCES in the electronic means of seeing and hearing, scientists and engineers scent a market for systems mimicking the human nose. Already commercial systems from several companies are targeting applications, present and potential, that range from quality assurance of food and drugs to medical diagnosis, environmental monitoring, safety and security, and military use.

The harnessing of electronics to measure odor is greatly to be desired. Human panels backed by gas chromatography and mass spectrometry (GC/MS) are helpful in quantifying smells, but they are time-consuming, expensive, and seldom performed in real time in the field. So it is important that these traditional methods give way to a speedier procedure using an electronic nose composed of gas sensors.

To be sure, gas sensors have been around for many years. But today's electronic nose technology goes several steps farther. Arrays of sensors that respond to a wide range of compounds are used, as well as advanced pattern recognition and artificial intelligence techniques, which enable users to readily extract relevant and reliable information. So-called electronic noses—systems that detect and identify odors and vapors, typically by linking chemical sensing devices with signal-processing and pattern-recognition subsystems—go for US $20 000 to $100 000 in Europe, the United States, and Japan, predominantly for laboratory use.

Advances in the technology have been made ever since the early 1980s when researchers at the University of Warwick in Coventry, England, developed sensor arrays for odor detection. Focused primarily on the sensor aspect of the problem, the initial research explored the use of metal oxide devices. Later work at Warwick University explored the use of conducting polymers. In both, sensing is based on conductivity changes. These early efforts have spawned several commercial enterprises. In August 1991, the pioneers organized an advanced research workshop in Reykjavik, Iceland, sponsored by the North Atlantic Treaty Organization. The workshop accelerated interest in the field, and by now there are many groups around the world working on electronic nose technology.

The Warwick pioneers envisioned an actual electronic equivalent of the mammalian olfactory system and dubbed their primitive analogs of it the electronic nose. So even though the electronic system resembles its biological counterpart none too closely, the "electronic nose"—or E-nose—label has been widely adopted around the world.

The biological nose

To begin to mimic the human apparatus, researchers have identified distinct steps that characterize the way humans smell (see "Design for smelling," p. 32). It all begins with sniffing, which moves air samples that contain molecules of odors past curved bony structures called turbinates.
The turbinates create turbulent airflow patterns that carry the mixture of volatile compounds to the thin mucus coating of the nose's olfactory epithelium, where ends of the nerve cells that sense odorants show up [Fig. 1].

The volatile organic compounds (VOCs) basic to odors reach the olfactory epithelium in gaseous form or else as a coating on the particles that fill the air we breathe. Particles of less than 1 μm across, each a potential carrier for adsorbed odorous VOCs, can linger in still air for weeks on end. And VOCs reach the olfactory epithelium not only from the nostrils but also from the mouth when food is chewed.

As VOCs and particles carrying VOCs pass over the mucus membrane lining the nose, they are trapped by the mucus and diffuse through to the next layer, namely, the epithelium, where the sensory cells lie in wait. The cells are covered in multiple cilia—hair-like structures with receptors located on the cells' outer membranes. Olfactory cells are specialized neurons that are replicated approximately every 30 days.

The transformation of a molecule into an odor begins when this odorant molecule, as it is called, binds to a receptor protein. The event initiates a cascade of enzymatic reactions that result in dephosphorylation of the cells membrane. (Ion pumps within the cell membrane keep the cell polarized in its rest, or steady state, with a typical rest potential of about 90 mV across the membrane.) There are more than 100 million protein receptors in all, and perhaps 1000 types. For example, one receptor type is sensitive to a small subset of odorants, one of which is the organic compound octanal.

The sensory cells in the epithelium respond by transmitting signals along neural "wires" called axons. Such an axon first traverses a small hole in a bony structure in the base of the skull, known as the cribiform plate. Then the rest of the neuron wends its way to the brain's olfactory bulb where it terminates in a cluster of neural networks called glomeruli.

The 2000 or so glomeruli of the olfactory bulb represent the first tier of central odor information processing. All sensory neurons containing a specific odorant receptor are thought to converge on two or three glomeruli in the olfactory bulb. Note that olfactory sensory neurons in the epithelium can each respond to more than one odorant. It is therefore the pattern of response across multiple glomeruli that codes olfactory quality.

Olfactory information ultimately arrives higher up in the brain, first at the hypothalamus, which also processes neural signals related to food intake, and then at still higher processing centers. The use of noninvasive techniques to study the brain suggests that different chemical stimuli activate different brain regions to different degrees.

As the new electronic technology emerges, conventional approaches to measuring odor are challenged. As noted earlier, current methods generally involve either the use of human odor panels to quantify and characterize the odor or gas chromatography and mass spectrometry to precisely identify the odorants producing it.

The concentration of an odor may be expressed as a multiple of either its detection or its recognition threshold. The detection threshold is defined by the American Society for Testing and Materials (ASTM) as the lowest concentration at which an odor is first detected—recognition is not necessary—by 50 percent of humans sniffing it. The detection threshold is considered the absolute threshold of sensation for an odor. The odor concentration at this threshold is defined to be 1.0 odor unit/m³. The value is established by averaging the responses over a population of individuals.

Panels of trained human "sniffers" are the gold standard of odor measurement. The recognition threshold is defined by ASTM as the lowest concentration at which an odor is first identified by 50 percent of the population sniffing an odorant. In this case, positive identification of the odor is required. The recognition threshold is often 5-10 odor units, or 5-10 times as high as the detection threshold.

[1] The human perception of odors begins with sniffing, which brings air samples that contain odorant molecules past curved bony structures in the nose called turbinates. These last create turbulent airflow patterns that allow the mixture of volatile organic compounds (VOCs) to reach a thin mucus layer coating the olfactory epithelium. The sensory cells for detecting odorants are part of the epithelium.

Gas chromatography and mass spectrometry have also been used to identify the chemical constituents of an odorous mixture. Air samples are collected in special canisters or bags and taken to the laboratory for analysis afterward. The odorant may be concentrated—in the field or laboratory—by using a vapor trap consisting of an absorbent material or cryogenic device.

In either case, a measured volume of the sample is forced through the trap, where odorant molecules are removed from the gas sample and collected on the absorbent material or cryogenic surface. Heating the trap releases the concentrated molecules rapidly into the gas chromatograph. Borne along on a small volume of a
pure carrier gas, which flows through the column at a constant rate, the sample passes through the column to a detector [see “Some gas chromatography and mass spectrometry basics,” p. 26].

Why electrify the nose?

Enter the gas sensors of the electronic nose. This speedy, reliable new technology undertakes what till now has been impossible—continuous real-time monitoring of odor at specific sites in the field over hours, days, weeks, or even months.

An electronic device can also circumvent many other problems associated with the use of human panels. Individual variability, adaptation (becoming less sensitive during prolonged exposure), fatigue, infections, mental state, subjectivity, and exposure to hazardous compounds all come to mind. In effect, the electronic nose can create odor-exposure profiles beyond the capabilities of the human panel or GC/MS measurement techniques.

The electronic nose is a system consisting of three functional components that operate serially on an odorant sample—a sample handler, an array of gas sensors, and a signal-processing system. The output of the electronic nose can be the identity of the odorant, an estimate of the concentration of the odorant, or the characteristic properties of the odor as might be perceived by a human.

Fundamental to the artificial nose is the idea that each sensor in the array has different sensitivity. For example, odorant No. 1 may produce a high response in one sensor and lower responses in others; whereas odorant No. 2 might produce high readings for sensors other than the one that ‘‘touched’’ odorant No. 1.

What is important is that the pattern of response across the sensors is distinct for different odorants. This distinguishability allows the system to identify an unknown odor from the pattern of sensor responses. Each sensor in the array has a unique response profile to the spectrum of odorants under test. The pattern of response across all sensors in the array is used to identify and/or characterize the odor.

Sensing an odorant

In a typical electronic nose, an air sample is pulled by a vacuum pump through a tube into a small chamber housing the electronic sensor array. The tube may be made of plastic or stainless steel.

Next, the sample-handling unit exposes the sensors to the odorant, producing a transient response as the VOCs interact with the surface and bulk of the sensor’s active material. (Earlier each sensor has been driven to a known state by having clean, dry air or some other reference gas passed over its active elements.) A steady-state condition is reached in a few seconds to a few minutes, depending on the sensor type.

During this interval, the sensor’s response is recorded and delivered to the signal-processing unit. Then, a washing gas such as an alcohol vapor is applied to the array for a few seconds to a minute, so as to remove the odorant mixture from the surface and bulk of the sensor’s active material. (Some designers choose to skip this washing step.)

Finally, the reference gas is again applied to the array, to prepare it for a new measurement cycle. The period during which the odorant is applied is called the response time of the sensor array. The period during which the washing and reference gases are applied is termed the recovery time.

**Defining terms**

Atomic mass: the average mass of an atom, expressed in atomic mass units (amu). The mass of an atom is determined by weighing the atom in a vacuum using a balance. The mass of an atom is usually expressed as a multiple of the mass of a carbon 12 atom.

Electronic nose: a system that simulates the pattern of response of an array of gas sensors to identify an odorant.

Gas chromatography: A method of separating a complex mixture of compounds into its individual components. The mixture is passed through a column (called a capillary) by a pure, inert carrier gas, in turn, the molecular constituents are separated and identified by their retention times and the emergence of the column as a series of constant compound peaks, by mass.

Mass spectrometry: A method of measuring the masses of different ions formed by the ionization of a substance. Ions are either detected by magnetic fields or separated by a set of electric and magnetic fields.

Odor: a sense organ represented when odorant (gas molecule) comes into contact with sensory receptors on the olfactory mucosa in the nasal cavity.

Odor detection threshold: the lower limit of concentration of an odorant that can be detected by the human nose.

Odor recognition threshold: the lower limit of concentration at which an odorant can be recognized by the human nose.

Odor unit: the lower limit of concentration at which an odorant can be detected by a person.

Olfaction: the sense of smell.

Olfactometer: an instrument for measuring the sensitivity of the sense of smell. It delivers vapors of odorants at constant concentrations to the nose of a test subject.

Olfactory neurons: nerve cell sensitive to odor. They receive a thin layer called the olfactory epithelium on the roof of the nasal cavity.

OQM sensor: an element of the MOS or MOSFET family of sensors that is configured as a gas or liquid-sensing element. The mass of an element is determined by the response to specific compounds and the sensor’s signal is amplified by a metal-oxide semiconductor.

Receptor: a molecular structure or the surface of a receptor for which specific compounds can interact with specific binding sites, and is detected by a metal-oxide semiconductor.

SAG sensor: another MOS or MOSFET family of sensors that is configured as a gas or liquid-sensing element. The mass of an element is determined by the response to specific compounds and the sensor’s signal is amplified by a metal-oxide semiconductor.

Vapor trap: a means of trapping odorants in a sample.

Volatile organic compound: any gas or vapor containing compound that can exist in vapor phase at room temperature. Such compounds are the major constituent of odorants and make up the bulk of the scent.
Starring the array

The sensor array is clearly the key element. As shown in Table 1, electronic nose sensors fall into five categories: conductivity sensors, piezoelectric sensors, MOSFETs, optical sensors, and spectrometry-based sensing methods.

There are two types of conductivity sensors: metal oxide and polymer, both of which exhibit a change in resistance when exposed to volatile organic compounds [Fig. 2]. Of the two types, metal oxide semiconductors have been used more extensively in electronic nose instruments and are widely available commercially. Typical offerings include oxides of tin, zinc, titanium, tungsten, and iridium, doped with a noble metal catalyst such as platinum or palladium.

The doped semiconducting material with which the VOCs interact is deposited between two metal contacts over a resistive heating element, which operates at 200 °C to 400 °C. At these elevated temperatures, heat dissipation becomes a factor in the mechanical design of the sensing chamber. Micromachining is often used to thin the sensor substrate under the active material, so that power consumption and heat dissipation requirements are reduced. As a VOC passes over the doped oxide material, the resistance between the two metal contacts changes in proportion to the concentration of the VOC.

The recipe for the active sensor material is designed to enhance the response to specific odors, such as carbon monoxide or ammonia. Selectivity can be further improved by altering the operating temperature. Sensor sensitivity ranges from 5 to 500 parts per million. The sensors also respond to water vapor, more specifically, to humidity differences between the gas sample being analyzed and a known reference gas used to initialize the sensor.

The baseline response of metal oxide sensors is prone to drift over periods of hours to days, so signal-processing algorithms should be employed to counteract this property. The sensors are also susceptible to poisoning (irreversible binding) by sulfur compounds present in the odorant mixture. But their wide availability and relatively low cost make them the most widely used gas sensors today.

Conducting polymer sensors, a second type of conductivity sensor, are also commonly used in electronic nose systems. Here, the active material in Fig. 2 is a conducting polymer from such families as the polypyrrroles, thiophenes, indoles, or furans. Changes in the conductivity of these materials occur as they are exposed to various types of chemicals, which bond with the polymer backbone. The bonding may be ionic or, in some cases, covalent. The interaction affects the transfer of electrons along the polymer chain, that is to say, its conductivity. A given compound's affinity for a polymer and its effects on the polymer's conductivity are strongly influenced by the counter-ions and functional groups attached to the polymer backbone.

In order to use these polymers in a sensor, contact micromachining techniques are employed to form two electrodes separated by a gap of 10 to 20 μm. Then the conducting polymer is electropolymerized between the electrodes by cycling the voltage between them. For example, layers of polypyrroles can be formed by cycling between -0.7 and +1.4 V. Varying the voltage sweep rate and applying a series of polymer precursors yields a wide variety of active materials. Response time is inversely proportional to the polymer's thickness. To speed response times, micrometer-size conducting-polymer bridges are formed between the contact electrodes.

Because conducting polymer sensors operate at ambient temperature, they do not need heaters and thus are easier to make. The electronic interface is straightforward, and they are suitable for portable instruments. The sensors can detect odors at sensitivities of 0.1 parts per million (ppm), but 10 to 100 ppm is more usual.

The main drawback of existing conducting-polymer sensors is that it is difficult and time-consuming to electropolymerize the active material, so they exhibit undesirable variations from one batch to another. Their responses also drift over time, and their usually greater sensitivity than metal oxides to water vapor renders them susceptible to humidity. This susceptibility can mask the responses to odorous volatile organic compounds.

In addition, some odors can penetrate the polymer bulk, dragging out the sensor recovery time by slowing the removal of the VOC from the polymer. This extends the cycle time for sequentially processing odorant samples.

[2] In a conductivity sensor, the usual active material is metal oxide or a conducting polymer. The electrodes may be platinum, aluminum, or gold, while the substrate may be of silicon, glass, or plastic. The heater, used only for metal oxide, is normally a platinum metal trace or wire. The interaction with VOCs alters the conductivity of the active material. The change in resistance across the electrode pair is then measured with a Wheatstone bridge or other circuitry (not shown).

[3] The quartz crystal microbalance (QCM) sensor is made of a polymer-coated resonating disk, a few millimeters in diameter, with metal electrodes on each side connected to lead wire. Gas molecules adsorbed to the surface of the polymer coating increase the mass of the disk, thereby reducing its resonance frequency.
Measuring mass changes

The piezoelectric family of sensors also has two members: quartz crystal microbalance (QCM) and surface acoustic-wave (SAW) devices. They can measure temperature, mass changes, pressure, force, and acceleration, but in the electronic nose, they are configured as mass-change-sensing devices.

The QCM types consist of a resonating disk a few millimeters in diameter, with metal electrodes on each side connected to a lead wire (Fig. 3). The device resonates at a characteristic frequency (10 MHz to 30 MHz) when excited with an oscillating signal.

During manufacture, a polymer coating is applied to the disk to serve as the active sensing material. In operation, a gas sample is adsorbed at the surface of the polymer, increasing the mass of the disk-polymer device and thereby reducing the resonance frequency. The reduction is inversely proportional to odorant mass adsorbed by the polymer. For example, a 166-μm-thick quartz crystal cut along a certain axis will resonate at 10 MHz. If a QCM sensor made with this resonator undergoes a positive 0.01 percent change in mass, a negative shift of 1 kHz will occur in its resonance frequency. Then when the sensor is exposed to a reference gas, the resonance frequency returns to its baseline value.

A good deal is known about QCM devices. The military, for one, has experimented with them for years, using them for the detection of trace amounts of explosives and other hazardous compounds and measuring mass changes to a resolution of 1 picogram. For example, 1 pg of methane in a 1-liter sample volume at standard temperature and pressure produces a methane concentration of 1.4 ppb.

![Diagram](image)

Some gas chromatography and mass spectrometry basics

A common type of gas chromatography (GC) column consists of a small capillary tube with an interior diameter of about 25 to 250 μm and a length of 1 to 30 meters. The inside wall of the hollow tube (the column) is coated with a thin polymeric film, from one-tenth to a few micrometers thick.

As odorants travel down the tube, the film interacts with the mixture, impeding its progress toward the outlet. The transport time delays of the various molecular constituents of the mixture vary with their vapor pressure and solubility, causing them to separate as they emerge from the column outlet.

Think of it as an auto race in which all the contestants begin at the same time in a group, but stretch out and arrive in single file at the finish line. Similarly, the transport time delay generates a molecular spectrum of constituents emerging from the end of the GC column.

A sensor at the end of the column generates a peak-shaped current response with the emergence of each of the constituent gases (elutes). The most common sensor is a flame ionization detector in which a flame heats a small gap between two wires, such that each constituent gas produces an electric current as it passes through the flame. The height and area of the peaks is a measure of the mass of each of the odorant constituents.

Furthermore, the molecules eluting from the column can be fragmented in a mass spectrometer (MS) to produce a characteristic pattern that aids in their identification. In the MS, each constituent compound molecule is ionized, typically by an electron beam, and the energy absorbed by the molecule in effect breaks it into fragments.

Just how a molecule fragments depends on its chemical structure and mode of ionization. These ions are injected into a mass filter that separates them according to their mass-to-charge ratio, yielding a quantitative measurement of each ion. The mass spectrum that results can be used to identify the original molecule.

The combination of a gas chromatograph followed by a mass spectrometer makes a powerful analytical tool. In brief, the GC column separates an odorant mixture into its molecular constituents, and the MS generates a mass spectrum for each peak.

The spectra are typically compared to spectra contained in a large chemical database to help identify the specific chemical compound in each constituent peak. The spectrum of labeled peaks with the concentration information from the gas chromatograph column is then used to distinguish the odorant mixture in the original sample.

—H.T.N. S.S.S. & R.G.O.
In addition, QCM sensors are remarkably linear over a wide dynamic range. Their response to water is dependent upon the absorbent materials employed, and their sensitivity to changes in temperature can be made negligible.

Tailoring the QCM for specific applications is done by adjusting its polymer coating. Fortunately, a large number of coatings is available from those developed for GC columns. The response and recovery times of the resonant structure are minimized by reducing the size and mass of the quartz crystal along with the thickness of the polymer coating. Batch-to-batch variability is not a problem because these devices measure normalized frequency change, a differential measurement that removes common-mode noise.

Care must be taken when making these three-dimensional devices by microelectromechanical system (MEMS) processing techniques. When the dimensions are scaled down to micrometer levels, the surface-to-volume ratios increase, and the larger the surface-to-volume ratio, the noisier the devices get because of surface processes that cause instabilities. Hence, signal-to-noise ratios degrade with increasing surface-to-volume ratio, thereby hampering measurement accuracy. It should be noted that this phenomenon applies to most microfabricated devices.

**Traveling over the surface**

QCMs, or SAW sensor, differs from it in several important ways. First, a Rayleigh (surface) wave travels over the surface of the device, not throughout its volume [Fig. 4]. SAW sensors operate at much higher frequencies, and so can generate a larger change in frequency. A typical SAW device operates in the hundreds of megahertz, while 10 MHz is more typical for a QCM, but SAW devices can measure changes in mass to the same order of magnitude as QCMs. Even though the frequency change is larger, increased surface-to-volume ratios mean the signal-to-noise ratio is usually poorer. Hence, SAW devices can be less sensitive than QCMs in some instances.

Being planar, SAW devices can be fabricated with photolithographic methods developed by the microelectronics industry. The fact that three-dimensional MEMS processing is unnecessary makes them relatively cheaper than their QCM counterparts when large quantities are produced.

As with QCMs, many polymer coatings are available, and as with the other sensor types, differential measurements can eliminate common-mode effects. For example, two adjacent SAW devices on the same substrate (one with an active membrane and another without) can be operated as a differential pair to remove temperature variations and power line noise.

A disadvantage of both QCM and SAW devices is more complex electronics than are needed by the conductivity sensors. Another is their need for frequency detectors, whose resonant frequencies can drift as the active membrane ages.
Olfactory signal processing and pattern recognition

The task of an electronic nose is to identify an odorant sample and perhaps to estimate its concentration. The measurement signal, odorant, and pattern recognition

For an electronic nose system, these two steps may be subdivided into two main stages: preprocessing, feature extraction, classification, and decision making. But first, a database of stored examples is established and the sample to be measured is presented to the nose's sensor array.

Preprocessing compresses the sensor drift, compensates the transient response of the sensor array, and reduces sample-to-sample variations. Typical techniques include data-flattening of sensor baseline normalization or removal of response ramps in all the sensors in an array. The normalization constant may sometimes be used to estimate the odorant concentration, and compression of sensor responses.

Feature extraction has two purposes: to reduce the dimensionality of the measurement signal and to remove information irrelevant for pattern recognition. This is done in an electronic nose with 32 sensors. The measurement space is 32 dimensions. This space can cause statistical problems if the odor database contains only a few examples, typical in pattern recognition applications because of the cost of data collection.

Furthermore, since the sensors possess overlapping sensitivities, there is a high degree of redundancy in these 32 dimensions. It is therefore convenient to project the 32 into a lower, more informative, and independent axes. This low-dimensional projection typically, two or three axes, has the added advantage that it can be more easily inspected visually.

Feature extraction is generally performed in one of two ways: either an algorithm such as the classical principal components analysis (PCA) and linear discriminant analysis (LDA).

PCA finds single-axis components that capture the greatest variability in the data and represents it in a lower-dimensional space maintained by the variance of the data. But it is not optimal for classification since it ignores the identity (class label) of the odor examples in the database. LDA, on the other hand, looks at the class labels of each example. Its goal is to find projections that maximize the separation between examples from different classes and do not minimize the variance between elements of the same odorant.

As an example, LDA may do better with a projection that contains high variance within a class and little variance between classes. LDA may work better with a projection that contains the opposite, but this requires careful statistical discrimination. Hence, LDA is therefore more appropriate for classification purposes.

Several research groups have recently adopted some nonlinear transforms such as Sigmoidal nonlinearities and Kohonen self-organizing spaces in the attempt to find a projection on the low-dimensional space that preserves the distances between pairs of examples on the original 32-dimensional space. Kohonen maps are low-dimensional space networks (typically 2-dimensional) that map input patterns to the output nodes based on the Euclidean distance between the pattern and the standard weights.

During training, the ANN adapts the weights to learn the patterns of the different classes. After training, when presented with an unidentified odorant, the Bayesian classifier will select the class that maximizes the precompiled probability distribution.

A typical ANN classifier consists of two or more layers of nodes that are connected with synaptic weights. Each number multiple the distance between the nodes. The output layer is used to classify the odorant.

The same method is used if any other sensory feedback is available, such as confidence thresholds or risk associated with different classification failures. The decision-making module may further limit the classifier assignment and even detect the odorant's concentration in parts per billion, not binding to any of the odors in the database.

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A MOSFET catalyzed

Metal-oxide-silicon field-effect-transistor (MOSFET) odor-sensing devices are based on the principle that VOCs in contact with a catalytic metal can produce a reaction in the metal. The reaction products can diffuse through the gate of a MOSFET to change the electrical properties of the device. A typical MOSFET structure has a p-type substrate with two n-doped regions with metal contacts labeled source and drain. The sensitivity and selectivity of the devices can be optimized by varying the type and thickness of the metal catalyst, and by operating them at different temperatures. MOSFET sensors have been investigated for numerous applications, but to date, few have been used in commercial electronic nose systems because of a dearth of sensor variants.

The advantage of MOSFETs is that they can be made with IC fabrication processes, so that batch-to-batch variations can be minimized. The disadvantage is that the catalyzed reaction products (such as hydrogen) must penetrate the catalytic metal layer in order to influence the change at the channel; the package must therefore have a window to permit gas to interact with the gate structure on the IC chip. Thus it is important to maintain a hermetic seal for the chip's electrical connections in harsh environments. This requirement may be satisfied by using photo-definable polymers, such as polyimide, to seal all areas of the chip that are not to be intentionally exposed to the environment. MOSFET sensors also undergo baseline drift similar to that of the conductivity sensors.

Optical-fiber sensors, yet another type, utilize glass fibers with a thin chemically active material coating on their sides or ends. A light source at a single frequency (or at a narrow band of frequencies) is used to interrogate the active material, which in turn responds with a change in color to the presence of the VOCs to be detected and measured.

The active material contains chemically active fluorescent dyes immobilized in an organic polymer matrix. As VOCs interact with it, the polarity of the fluorescent dyes is altered and they respond by shifting their fluorescent emission spectrum. When a pulse of light from an external source interrogates the sensor, the fluorescent dye responds by emitting light at a different frequency. As the source intensity is much greater than the sensor response, great care must be taken to ensure that the response photodetectors are protected from the source emissions.

Arrays of these devices with different dye mixtures can be used as sensors for an electronic nose. For example, researchers at Tufts University in Medford, Mass., have constructed an optical system that interrogates the sensors at an excitation wavelength of 535 nm, and measures time and amplitude changes in fluorescence emission wavelength at 610 nm.

Favoring optical-fiber sensors is the availability of many different dyes for biological research, so that the sensors themselves are cheap and easy to fabricate. It is also possible to couple fluorescent dyes to antibody-antigen binding the recognition of a specific molecule, and only that molecule, as in the human immune sys-

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<td>Sample not consumed</td>
<td>Requires tunable quantum-well devices</td>
</tr>
</tbody>
</table>

MEMS = microelectromechanical system

NAGLE, SCHIFFMAN & GUTIERREZ-OSLINA — ELECTRONIC NOSES
tem.) Thus an array of fiber sensors can have wide-ranging sensitivities, a feature not easily obtainable with other sensor types. As with other types, differential measurements can also be used to remove common-mode noise effects.

In their disfavor are the complexity of the instrumentation control system, which adds to fabrication costs, and their limited lifetime due to photebleaching. The fluorescent dyes are slowly consumed by the sensing process, the way sunlight bleaches fabric dyes.

**Spectral mockups**

Still other approaches to developing sensor arrays have been suggested, resulting in what may be called spectrometric pseudo-sensor arrays. The first operation is to use a vapor trap to concentrate the VOCs, as is done for GC columns. The concentrated vapor is then injected into a spectrometer that generates a spectral response characteristic of the vapor. That response may take many forms, such as separated molecular constituents (as in the gas chromatograph column), atomic mass profile (as in the mass spectrometer), or transmitted light frequencies.

The last approach may be implemented by acousto-optic tunable filters (AOTFs), which alter their light-filtering characteristics in response to a change in voltage across their light-transmission path. Sweeping the voltage controlling the device effectually changes the transmission path through the filter and so changes its peak wavelength. The result is a time-varying signal that is a function of the light spectrum of the incoming source.

For all three spectrometer types, a sensor at the output detects a characteristic profile for each odorant being examined. This profile may be viewed as a uniquely varying pattern that, when sampled at various instants, creates an array of data that apparently comes from different parallel sensors, hence they may be called apparent, or pseudo, sensors. The process is like using a shift register in a computer to convert a serial bit-stream into a parallel data word.

Data points representing the pseudo-sensors can be used by signal-processing algorithms as effectively as data from the physical sensor arrays described earlier. In fact, the odorant mixture can be separated in a few seconds into constituents with analytical accuracy. On the other hand, a vapor trap is usually required to increase the sample concentration that can alter the characteristics of the odor. They also require complex electronics for instrument control.

**Close to hand**

Many electronic nose systems are now available, including those listed in Table 2. Since much of the early work using this technology in various applications has been carried out in Britain, many of the commercially available machines originated there, at companies such as AromaScan, Bloodhound Sensors, and EEV Chemical Sensor Systems.

Other European competitors include Germany’s Lemertz, France’s Alpha M.O.S., and Sweden’s Nordic Sensor Technologies. In the United States, there are Cyrano Sensors, Electronic Sensor Technologies, Hewlett-Packard, and MicroSensor Systems, while several Japanese companies are also developing systems.

Most of the machines listed in the table are priced from US $20 000–$100 000, but prices should drop in a few years as competition heats up and sensor technology improves. Most models on the market are fairly large, none too portable, lab-type systems, but several manufacturers have said they are working on miniaturized versions.

**A manifold appeal**

The electronic nose has been used in a variety of applications and could help solve problems in many fields, including food product quality assurance, health care, environmental monitoring, pharmaceuticals, indoor air quality, safety and security, and the military. However, for the electronic nose to succeed in those areas, there need to be marked improvements in technology.

The electronic nose can be applied by food manufacturers to such tasks as freshness testing, quality control, and screening of incoming raw materials, not to mention feedback control to optimize bioreactors and minimize batch variation, and monitoring for accidental or intentional contamination or mislabeling of manufactured food products.

For example, at North Carolina State University we have used an experimental prototype to analyze the odors of several types of coffee beans (Fig. 7). We employed signal-processing and pattern recognition routines to transform and display sensor data [see “Olfactory signal processing and pattern recognition,” p. 28]. Electronic nose systems are well suited to comparing final products to reference standards, even replacing human taste panels in some applications. Testing of food freshness is especially important for the elderly since their senses of taste and smell dull with advancing age.

Odor has been valued for centuries by physicians for diagnostic purposes. An electronic nose could be used to analyze breath, sweat, urine, and stools, and some of

![Graphical representation of probability distribution](image-url)
## 2. Available electronic nose Instruments

<table>
<thead>
<tr>
<th>Manufacturer</th>
<th>Place of origin</th>
<th>Sensor type</th>
<th>No. of sensors</th>
<th>Size of instrument</th>
<th>Auto-sample available?</th>
<th>Pattern recognition</th>
<th>Cost, US $</th>
<th>How to contact</th>
</tr>
</thead>
<tbody>
<tr>
<td>Aisense Analysis GmbH</td>
<td>Germany (Schwerin)</td>
<td>Metal oxide semiconductor (MOS)</td>
<td>10</td>
<td>Laptop</td>
<td>Yes</td>
<td>Artificial neural network (ANN), distance classifiers (DC), principal component analysis (PCA), statistical pattern recognition (SPR)</td>
<td>20,000-43,000 (no auto-sampler)</td>
<td><a href="http://www.aisense.com">www.aisense.com</a> (49+285) 63 44 280 fax, 63 44 281</td>
</tr>
<tr>
<td>Alpha MOS-Multi Organolectic Systems</td>
<td>France (Toulouse)</td>
<td>Conducting polymer (CP), MOS, quartz crystal microbalance (QCM) surface acoustic wave (SAW)</td>
<td>6-24</td>
<td>Desktop</td>
<td>Yes</td>
<td>ANN, discriminant function analysis (DFA), PCA</td>
<td>20,000-100,000</td>
<td><a href="http://www.ALPHA-mos.com">www.ALPHA-mos.com</a> (33 +5) 62 47 53 80 fax, 61 54 56 15</td>
</tr>
<tr>
<td>AromaScan PLC</td>
<td>UK (Crewie)</td>
<td>CP</td>
<td>32</td>
<td>Desktop</td>
<td>Yes</td>
<td>ANN</td>
<td>20,000-75,000</td>
<td><a href="http://www.aromascan.com">www.aromascan.com</a> atHome.html (44+1279) 021 6444 fax, 021 6030</td>
</tr>
<tr>
<td>Bloodhound Sensors Ltd.</td>
<td>UK (Leeds)</td>
<td>CP</td>
<td>14</td>
<td>Laptop</td>
<td>No</td>
<td>ANN, cluster analysis (CA), PCA</td>
<td>—</td>
<td><a href="http://www.bloodhound.co.uk/bloodhound">www.bloodhound.co.uk/bloodhound</a> (44+113) 233 3439 fax, 233 3433</td>
</tr>
<tr>
<td>Cyranosciences Inc.</td>
<td>United States (Pasadena, Calif.)</td>
<td>CPI</td>
<td>32</td>
<td>Palmtop</td>
<td>No</td>
<td>PCA</td>
<td>5000</td>
<td><a href="http://www.cyranosciences.com">www.cyranosciences.com</a></td>
</tr>
<tr>
<td>EEV Ltd. Chemical Sensor Systems</td>
<td>UK (Chelmsford)</td>
<td>CP, MOS, QCM, SAW</td>
<td>8-28</td>
<td>Desktop</td>
<td>Yes</td>
<td>ANN, DFA, PCA, proprietary algorithm</td>
<td>—</td>
<td><a href="http://www.eev.com">www.eev.com</a> Europe: (44+1279) 87 1659 fax, 87 1662 United States: (800) 535 0606 fax, (770) 967 1854</td>
</tr>
<tr>
<td>Electronic Sensor Technology Inc.</td>
<td>United States (Newbury Park, Calif.)</td>
<td>Gas chromatography (GC) column, SAW</td>
<td>1</td>
<td>Desktop</td>
<td>No1</td>
<td>SPR</td>
<td>19,500-25,000</td>
<td><a href="http://www.escal.com/">www.escal.com/</a></td>
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<tr>
<td>HKB-Sensor systems GmbH</td>
<td>Germany (Munich)</td>
<td>QCM</td>
<td>6</td>
<td>Desktop</td>
<td>Yes</td>
<td>ANN, CA, DFA, PCA</td>
<td>—</td>
<td>home.t-online.de/home/hkbsensor (49+49) 746 02 07 fax, 746 02 08</td>
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<tr>
<td>Lennartz Electronic GmbH</td>
<td>Germany (Tibingen)</td>
<td>MOS, QCM</td>
<td>16-40</td>
<td>Desktop</td>
<td>Yes</td>
<td>ANN, PCA, principal components regression (PCR)</td>
<td>55,000</td>
<td><a href="http://www.lennartz-electronic.de/">www.lennartz-electronic.de/</a> (49071) 93550 fax, 935530</td>
</tr>
<tr>
<td>Nordic Sensor Technologies AB</td>
<td>Sweden (Linköping)</td>
<td>Infrared (IR), MOS, MOSFET, QCM</td>
<td>22</td>
<td>Laptop</td>
<td>Yes</td>
<td>ANN, PCA</td>
<td>40,000-60,000</td>
<td><a href="http://www.nordicsensor.com">www.nordicsensor.com</a> (46+13) 212 990 fax, 212 905</td>
</tr>
<tr>
<td>RST Rostock Raumfahrt und Umweltschatz GmbH</td>
<td>Germany (Rostock)</td>
<td>MOS, QCM, SAW</td>
<td>6-10</td>
<td>Desktop</td>
<td>Yes</td>
<td>ANN, PCA</td>
<td>50,000</td>
<td><a href="http://www.rst-rostock.de">www.rst-rostock.de</a> (49+381) 56-0 fax, 56-202</td>
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<tr>
<td>Sawtek inc.</td>
<td>United States (Bowling Green, Ky.)</td>
<td>SAW</td>
<td>2</td>
<td>Palmtop</td>
<td>No</td>
<td>Proprietary</td>
<td>5000</td>
<td><a href="http://www.microsensor">www.microsensor</a> systems.com (407) 886 8860 fax, 886 7061</td>
</tr>
</tbody>
</table>

1 The sensors are made of polymer conductive composites.
2 Available summer 1999.
3 The vendor does not market an auto-sampler, but its instrument can be interfaced with third-party auto-sampling stages.
4 Price information upon request; prices start at about US $55,000.